

IWA TG on Benchmarking of Control Strategies for WWTPs

Simulation of control strategies – dynamic modelling of sensor and actuator behaviour

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Beijing, PR China

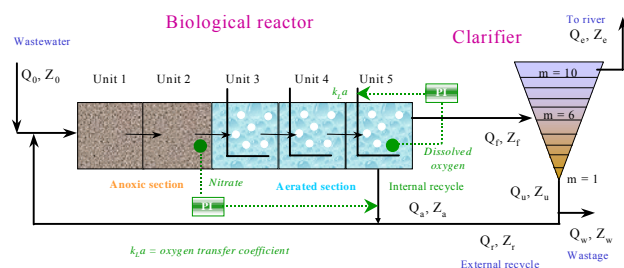
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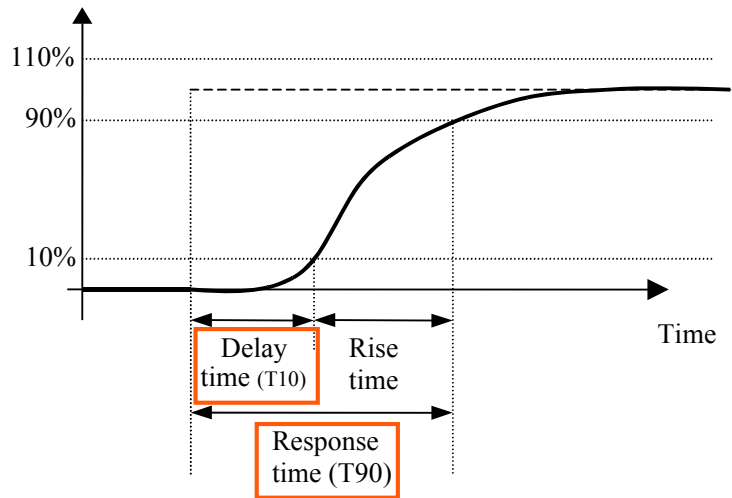
Introduction

- Sensors and actuators necessary for monitoring and control
- They are themselves complex systems and have their own dynamics



Sensors

According to ISO 2003 norm



Measuring range

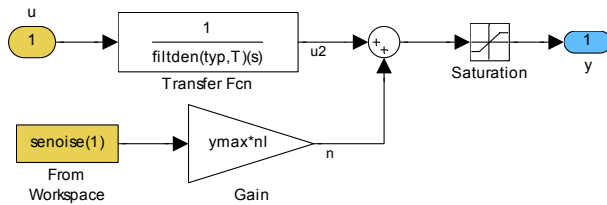
Noise : random noise, standard deviation = 1, x noise level (2.5% of range)

Sensor classes

Sensor classes	Response time (T90) [min]	Measuring interval (T0) [min]	Examples
Class A	1	0	Ion sensitive, optical without filtration
Class B ₀	10	0	Gas sensitive + fast filtration
Class B ₁	10	5	Photometric + fast filtration
Class C ₀	20	0	Gas-sensitive + slow filtration
Class C ₁	20	5	Photometric + slow filtration or sedimentation
Class D	30	30	Photometric or titrimetric for total components

Programming a simple sensor ...

For Matlab/Simulink



$$\frac{d x_1(t)}{dt} = \frac{1}{T} u(t) - \frac{1}{T} x_1(t)$$

$$\frac{d u_2(t)}{dt} = \frac{1}{T} x_1(t) - \frac{1}{T} u_2(t)$$

$$y_1(t) = u_2(t) + y_{\max} nl n(t)$$

$$y(t) = \begin{cases} y_1(t) > y_{\max} : y_{\max} \\ y_{\min} < y_1(t) < y_{\max} : y_1(t) \\ y_1(t) < y_{\min} : y_{\min} \end{cases}$$

Recommended BSM1 sensor parameters

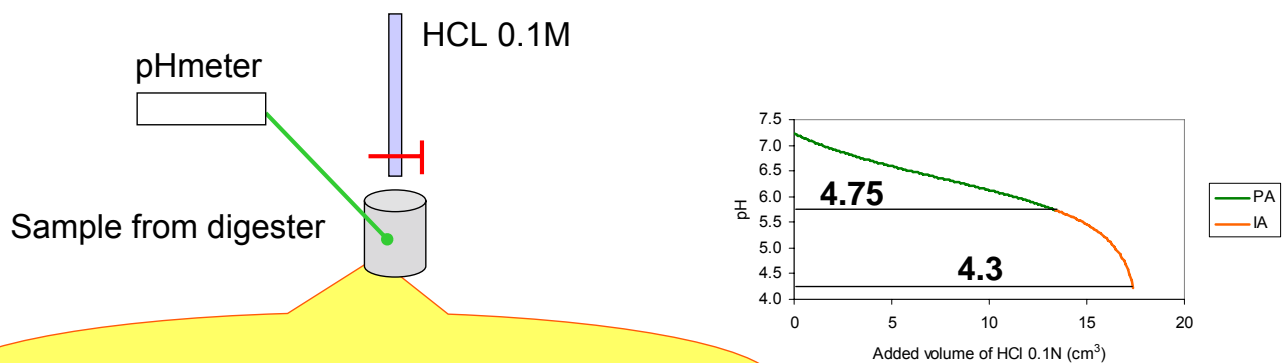
Measured variable	Class	Measurement Range	Measurement noise (δ)
Flow rate (m ³ /d) high range	A	0-100 000 m ³ /d	2500
Water level (m)	A	0-5 m	0.125
Temperature (°C)	A	5-25 °C	0.5
pH	A	5-9	0.1
S _O (mg O ₂ /l)	A	0-10	0.25
Sludge blanket level (m)	A	0-5	0.125
S _{NO} (mg N/l)	B0	0-20	0.5
S _{NH} (mg N/l) low range	B0	0-20	0.5
S _{NH} (mg N/l) high range	B0	0-50	1.25
S _{ALK} (mol HCO ₃ /m ³)	B0	0-20	0.5
Mixed-liquor suspended solids (mg/l)	A	0-10 000	250
Effluent total suspended solids (mg/l)	A	0-200	5
Total COD (mg COD/l)	D	0-1 000	25
OUR (mg/(l·d))	D	0-2 000	50

You can still program (with care) your own sensors ...

- Purpose: test of the effect of sensor design / operation parameters
- Respirometer (OUR, toxicity detection) or other batch tests (nitrification potential, ...)
- Settleability
- Titrimeter

Example of a detailed simulation

Titrimetric sensor for digester monitoring (BSM2)

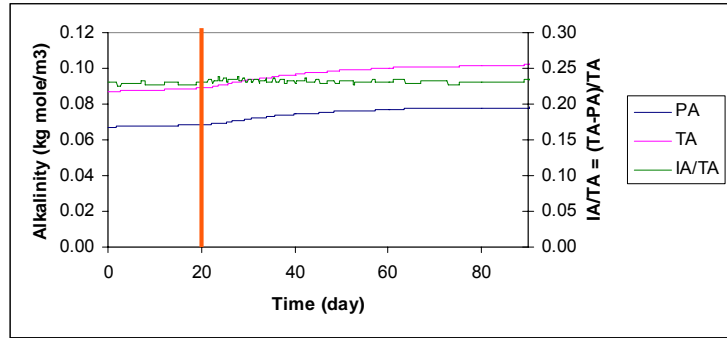


Calculation of pH for every drop of HCL added

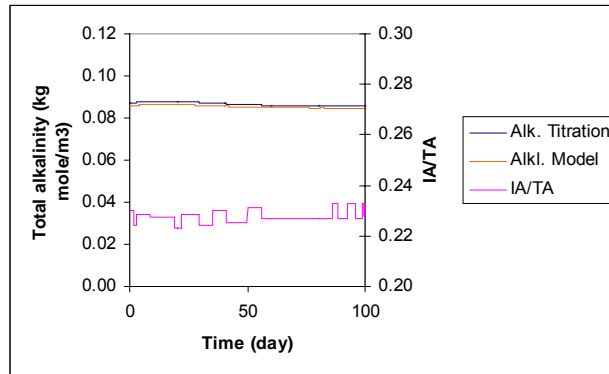
- Algebraic equation (Pons et al., Talanta, 1983)
- Minimization of $|\sum \text{anions} - \sum \text{cations}|$ wrt pH
 - Golden Section method

Results

- Flowrate increase



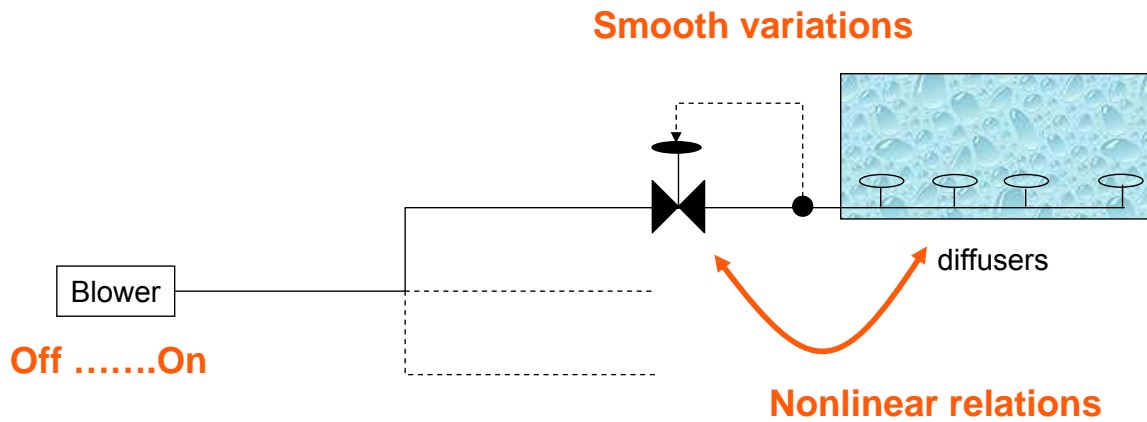
- Dynamic behavior



Actuators – control handles

- internal flow recirculation rate
 - return sludge flow rate
 - wastage flow rate
 - aeration intensity individually
 - external carbon source flow rate
 - anoxic/aerobic volume
 - influent distribution by use of step feed
 - distribution of internal flow recirculation
 - distribution of return sludge flow
- } 1st and 2nd order systems

Aeration control could receive more attention



Conclusions

- Sensors and actuators important part of the control strategy
- Affect the control performance
- Precise description needed